

SE524/EC524 Optimization Theory and Methods

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Lecture 23: Outline

- Practical Guidelines for solving LPs.
- Case study: The fleet assignment problem.

Practical Guidelines for LPs

- Exploit sparsity.
- Start with a “good” basis in simplex.
- Use of dual simplex.
- Use of interior point methods. Simplex or interior point method ?

Fleet assignment

Given fleet and flight schedule **assign aircraft to flights**.

Fleet information

- \mathcal{F} : set of fleets.
- $S(f)$: # of aircraft in fleet $f \in \mathcal{F}$.

Fleet assignment (cont.)

Schedule information

- \mathcal{C} : set of cities served
- \mathcal{L} : set of flights
- $(o, d, t) \in \mathcal{L}$: (origin, dest., dep. time)
- c_{fodt} : cost
- t_0 : reference time
- (t_1, \dots, t_n) : time partition
- t^-, t^+
- $t(f, o, d)$: time that fleet f does $o-d$
- $O(t_0)$: set of flights on the air in $[t_0, t_0^+]$
- \mathcal{H} : set of "required through" pairs of flights (to be served by same fleet)

Formulation

Objective: Minimize cost

Decision variables

$$x_{fodt} = \begin{cases} 1 & \text{if fleet } f \text{ for } (o, d, t) \\ 0 & \text{otherwise} \end{cases}$$

$y_{fot} = \#$ of aircraft from f on ground in o during $[t, t^+]$

$z_{fot} = \#$ of aircraft from f that arrive in o at t

Formulation (cont.)

$$\begin{aligned}
 & \min \sum_{f \in \mathcal{F}} \sum_{(o,d,t) \in \mathcal{L}} c_{fodt} x_{fodt} \\
 & \sum_{f \in \mathcal{F}} x_{fodt} = 1 \quad \forall (o, d, t) \in \mathcal{L} \\
 & z_{fot} + y_{fot}^- - \sum_{d \in \mathcal{C}} x_{fodt} - y_{fot} = 0 \quad \forall f, o, t \\
 & x_{fodt} - x_{fdd't'} = 0 \quad \forall f \in \mathcal{F}, ((o, d, t), (d, d', t')) \in \mathcal{H} \\
 & \sum_{(o,d,t) \in \mathcal{O}(t_0)} x_{fodt} + \sum_{o \in \mathcal{C}} y_{fot_0} \leq S(f) \quad \forall f \in \mathcal{F} \\
 & z_{fot} = \sum_{\{(d,o,\tau) \in \mathcal{L} \mid \tau + t(f,d,o) = t\}} x_{fdor} \\
 & x_{fodt} \in \{0, 1\}, y_{fot} \geq 0, y_{fot} : \text{integer}
 \end{aligned}$$

Algorithm

- ➊ Preprocessing.
- ➋ Perturb all costs.
- ➌ Dual simplex or path following on LP relaxation.
- ➍ Remove perturbation.
- ➎ Reoptimize with original cost.
- ➏ Round variables above 0.99 to 1.
- ➐ Preprocessing.
- ➑ Dual simplex.
- ➒ Branch and bound.